# TABLE OF CONTENTS

	SESAM	E Project Planning	Page No.
1.	INTRO	DUCTION	1-1
2.	CHARA	CHARACTERISTICS OF SYNCHROTRON RADIATION	
	2.1	Introduction	2-1
	2.2	Radiation from a Bending Magnet	2-2
	2.3	Radiation from a Wiggler	2-5
	2.4	Radiation of an Undulator	2-10
3.	UPGRADING OF BESSY I		3-1
	3.1	Introduction	3-1
	3.2	Performance of a Synchrotron Light Source	3-1
	3.2.1	Spectral Range of the Synchrotron Radiation	3-1
	3.2.2	Brilliance of the Radiation	3-2
	3.2.3	Number of Experimental Stations	3-2
	3.3	Upgrading Versions of BESSY I	3-2
	3.3.1	Green Book (GB) Proposal for Upgrading SESAME to 1GeV	3-2
	3.3.2	White-Book (WB) Proposal for Upgrading SESAME to 2 GeV	3-4
	3.3.3	Yellow-Book (YB) Proposal for Upgrading SESAME to 2.5 GeV	3-6
	3.4	Comparison of the Different Versions	3-8
	3.4.1	Magnets	3-8
	3.4.2	Performance of the Different Upgrading Versions	3-8
		References	3-9
4.	BEAM OPTICS		4-1
	4.1	Introduction	4-1
	4.2	The Lattice	4-1
	4.2.1	The Unit Cell	4-1
	4.2.2	The Lattice Optimisation	4-4
	4.2.2.1	Choice of Working Point	4-5
	4.2.2.2	The Tune Shift with Amplitude	4-8
	4.2.2.3	The Dynamic Aperture	4-8
	4.2.2.4	The Off-momentum Dynamics	4-10
	4.2.3	The Machine Acceptance	4-14
	4.3	Effect of Insertion Devices on SESAME Optics	4-17
	4.3.1	Choosing the Optimum Optics	4-17
	4.3.2	The Compensation for the Undesirable Effects	4-21
	4.4	Closed Orbit Distortion and Correction	4-26

#### **SESAME** 4.5 The Coupling 4-29 Specifications of the Magnets 4-29 4.6 The Bending Magnets 4.6.1 4-30 4.6.2 The Quadrupole Magnets 4-30 The Sextupole Magnets 4-30 4.6.3 4.6.4 The Corrector Magnets 4-30 4.7 The Beam Lifetime 4-31 4-31 4.7.1 The Gas Scattering Lifetime 4.7.1.1 Elastic Nucleus-Scattering Lifetime (τcoul) 4-31 4.7.1.2 Elastic Shelf Electron-Scattering Lifetime (τcoul (e)) 4-31 4.7.1.3 Inelastic Nucleus-Scattering Lifetime (tbrem) 4-32 4.7.1.4 Inelastic Shelf Electron-Scattering Lifetime (τbrem (e)) 4-32 4.7.1.5 The Total Gas Scattering Lifetime 4-32 Touschek Scattering Lifetime 4.7.2 4-32 The Total Beam Lifetime 4-33 4.7.3 References 4-34 **5.** LAYOUT OF THE STORAGE RING 5-1 5.1 Introduction 5-1 5.2 Description of the SESAME Storage Ring 5-1 5.3 Choice of Material 5-7 5.4 Pre-Dipole Vacuum Chamber 5-7 5.5 **Dipole Vacuum Chambers** 5-9 5.6 **Straight Sections** 5-10 5.7 Bellows and Gate Valves 5-12 Synchrotron Radiation and Absorbers 5.8 5-14 5-19 References **6. MAGNETS** 6-1 Introduction 6-1 6.1 Bending Magnet 6.2 6-2 6.3 Quadrupole 6-7 6.4 Sextupole 6-9 6.5 Correctors 6-11 Girder System 6-11 6.6 7. **VACUUM SYSTEM** 7-1 7.1 Introduction 7-1 7.2 **SESAME** Parameters 7-1 7.3 Requirements 7-1 7.4 7-2 General Layout 7.5 Materials for the Vacuum Chamber 7-4 7.5.1 **Proprieties** 7-4 Vacuum Performance 7-4 7.5.1.1 **Mechanical Properties** 7.5.1.2 7-4

	7.5.2	Flanges and Gaskets	7-5
	7.6	Vacuum Chamber Design	7-5
	7.7	Pumps Selection	7-6
	7.7.1	Rough Pumping	7-6
	7.7.2	UHV Pumps	7-7
	7.8	Vacuum Instrumentation	7-8
	7.8.1	Total Pressure Gauges	7-8
	7.8.2	Partial Pressure Gauges	7-9
	7.9	Cleaning, Bakeout of Infrastructure	7-11
	7.10	Assembly	7-12
	7.11	Pressure Profile Calculations	7-12
	7.11.1	Gas Load Generation and Desorption Processes	7-13
	7.11.1.1	Thermal Desorption	7-13
	7.11.1.2	Photon Stimulated Desorption (PSD)	7-13
	7.11.2	Photon Flux from the Dipole	7-14
	7.11.3	Photon Stimulated Desorption Yield for SESAME (PSD)	7-16
	7.11.4	Desorption Flux	7-17
	7.11.5	The Achromat Pressure Profile	7-18
	7.11.5.1	Pumps Pumping Speed and the Average Dynamic Pressure	7-18
	7.11.5.2	Changes of the Pumps Pumping Speed and the Average	7-20
		Dynamic Pressure Achieved.	
	7.11.5.3	Average Dynamic Pressure of the Achromat During	7-20
		Commissioning and Operation of the Machine.	
	7.12	SESAME Microtron Vacuum System	7-22
		References	7-22
8.	RADIO	FREQUENCY SYSTEM	
	8.1	Introduction	8-1
	8.2	Components of the RF-System	8-2
	8.2.1	Cavities	8-2
	8.2.2	Klystron	8-4
	8.2.3	Waveguide System	8-4
	8.2.4	Low level Electronics	8-5
	8.2.5	Principle of Operation	8-5
	8.3	RF System Parameters	8-6
	8.3.1	Parameters of the Stored Beam	8-6
	8.3.2	Parameters of the Power System	8-9
	8.4	Low level Electronics	8-11
	8.4.1	Amplitude Loop	8-11
	8.4.2	Phase Loop	8-12
	8.4.3	Tuning Loop	8-13
9.	POWER	SUPPLIES	9-1
	9.1	Introduction	9-1
	9.2	Storage Ring Power Supplies	9-1

9.2.1	Specifications of the Existing Power Supplies	9-1
9.2.2	Specifications of the New Power Supplies	9-3
9.2.3	Power Converter Topologies	9-3
9.2.3.1	Linear Power Converter	9-3
9.2.3.2	Line Commutated Thyristor Power Converter	9-4
9.2.3.3	Switched-Mode Power Converter	9-6
9.2.3.3.1	Chopped DC Regulator	9-7
9.2.3.3.2	Resonant Converter	9-8
9.2.4	Power Converter Selection for SESAME	9-9
9.2.4.1	Dipole Power Converter	9-9
9.2.4.2	Quadrupole and Sextupole Power Converters	9-10
9.2.5	Pole Face Winding Power Supplies	9-10
9.3	Booster Power Supplies	9-10
9.3.1	Discussion about the Waveforms	9-11
9.3.2	Specifications of the Booster Power Supplies	9-12
9.3.3	Dipole Magnet Power Supply	9-13
9.4	Correction Power Supplies	9-13
9.4.1	Correction Power Supplies of the Storage Ring	9-13
9.4.2	Correction Power Supplies of the Booster	9-14
9.5	Power Supplies of the Transfer Lines	9-14
9.6	Disturbances to the Mains	9-15
9.7	Electronics of the Power Supplies	9-15
9.7.1	Introduction	9-15
9.7.2	Conventional Analog Electronic	9-15
9.7.3	Modern Digital electronics	9-17
9.7.4	Recommendations for SESAME	9-18
9.8	Magnet Cables	9-18
9.8.1	Cable Conductors and Sizes	9-18
9.8.2	Cable Losses	9-18
9.8.3	Connection of the Magnets	9-19
9.8.4	Cable Trays	9-21
9.9	Location of the Power Supplies	9-21
	References	9-22
10	DIA GNIGGERIGG	10.1
10.	DIAGNOSTICS	10-1
10.1	Introduction	10-1
10.2	Instrumentation	10-1
10.3	Measurement Procedures	10-2
10.3.1	Beam Intensity and Time Structure	10-2
10.3.2	Beam Position	10-2
10.3.3	Transverse and Longitudinal Particle Distribution	10-3
10.3.4	Lattice Functions, Tune and Dynamic Aperture	10-3
10.3.5	Measurement of Other Accelerator Parameters	10-3
10.4	Diagnostic System of SESAME	10-3
10.4.1	Fluorescent Screens	10-5

10.4.2 10.4.3 10.4.4 10.4.5 10.4.6 10.4.7 10.4.8 10.4.9	Beam Current Monitors Current Transformer Strip Lines Scrapers Beam Position Monitors Beam Loss Monitor Synchrotron Light Monitors Other Instrumentation References	10-5 10-6 10-6 10-7 10-9 10-9 10-9
11.	INJECTOR	11-1
11.1	Introduction	11-1
11.2	Microtron	11-1
11.3	Booster Synchrotron	11-3
11.4	Transfer Line	11-6
11.4.1	Lattice of the Transfer Line	11-6
11.4.2	Instrumentation of the Transfer Line	11-11
11.5	Injection of the Storage Ring	11-11
11.5.1	Optimization of the Placement of the Kickers	11-13
11.5.2	Injection Efficiency Studies and Simulation of Injection	11-13
	Process.	
	References	11-15
12.	CONTROL SYSTEM	12-1
12.1	Executive Summary	12-1
400	Introduction	12-2
12.2		12-2
12.2 12.3	Scopes of the Controls	12-2
12.3	Scopes of the Controls	12-3
12.3 12.4	Scopes of the Controls General Requirements	12-3 12-3
12.3 12.4 12.4.1	Scopes of the Controls General Requirements User Requirements	12-3 12-3 12-3
12.3 12.4 12.4.1 12.4.2	Scopes of the Controls General Requirements User Requirements System Requirements	12-3 12-3 12-4
12.3 12.4 12.4.1 12.4.2 12.4.2.1	Scopes of the Controls General Requirements User Requirements System Requirements Architecture	12-3 12-3 12-3 12-4 12-4
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer	12-3 12-3 12-3 12-4 12-4 12-6 12-6
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2 12.4.2.3	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer Software Layer	12-3 12-3 12-3 12-4 12-4 12-6 12-6
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2 12.4.2.3 12.4.2.4	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer Software Layer Applications with Graphical User Interface The Databases Subsystems	12-3 12-3 12-3 12-4 12-4 12-6 12-6 12-6 12-9 12-11
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2 12.4.2.3 12.4.2.4 12.4.2.5 12.5.1	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer Software Layer Applications with Graphical User Interface The Databases Subsystems Timing System	12-3 12-3 12-3 12-4 12-4 12-6 12-6 12-6 12-9 12-11
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2 12.4.2.3 12.4.2.4 12.4.2.5 12.5 12.5.1 12.5.1.1	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer Software Layer Applications with Graphical User Interface The Databases Subsystems Timing System Architecture	12-3 12-3 12-3 12-4 12-4 12-6 12-6 12-6 12-9 12-11 12-11
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2 12.4.2.3 12.4.2.4 12.4.2.5 12.5 12.5.1 12.5.1.1 12.5.2	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer Software Layer Applications with Graphical User Interface The Databases Subsystems Timing System Architecture Diagnostics	12-3 12-3 12-3 12-4 12-4 12-6 12-6 12-6 12-9 12-11 12-11 12-11
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2 12.4.2.3 12.4.2.4 12.4.2.5 12.5.1 12.5.1.1 12.5.2 12.5.3	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer Software Layer Applications with Graphical User Interface The Databases Subsystems Timing System Architecture Diagnostics Beam Line Controls	12-3 12-3 12-3 12-4 12-4 12-6 12-6 12-6 12-9 12-11 12-11 12-11 12-11
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2 12.4.2.3 12.4.2.4 12.4.2.5 12.5 12.5.1 12.5.1.1 12.5.2 12.5.3 12.6	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer Software Layer Applications with Graphical User Interface The Databases Subsystems Timing System Architecture Diagnostics Beam Line Controls The Control System for the Pre-injector (Microtron)	12-3 12-3 12-3 12-4 12-4 12-6 12-6 12-6 12-9 12-11 12-11 12-11 12-11 12-12 12-16
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2 12.4.2.3 12.4.2.4 12.4.2.5 12.5.1 12.5.1.1 12.5.2 12.5.3 12.6 12.6.1	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer Software Layer Applications with Graphical User Interface The Databases Subsystems Timing System Architecture Diagnostics Beam Line Controls The Control System for the Pre-injector (Microtron) Power Supplies (PS)	12-3 12-3 12-3 12-4 12-4 12-6 12-6 12-6 12-9 12-11 12-11 12-11 12-11 12-12 12-16 12-17
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2 12.4.2.3 12.4.2.4 12.4.2.5 12.5.1 12.5.1.1 12.5.2 12.5.3 12.6 12.6.1 12.6.1.1	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer Software Layer Applications with Graphical User Interface The Databases Subsystems Timing System Architecture Diagnostics Beam Line Controls The Control System for the Pre-injector (Microtron) Power Supplies (PS) Digital PS with Fibre-Optics Bus Approach	12-3 12-3 12-3 12-4 12-4 12-6 12-6 12-6 12-9 12-11 12-11 12-11 12-11 12-12 12-16 12-17
12.3 12.4 12.4.1 12.4.2 12.4.2.1 12.4.2.2 12.4.2.3 12.4.2.4 12.4.2.5 12.5.1 12.5.1.1 12.5.2 12.5.3 12.6 12.6.1	Scopes of the Controls General Requirements User Requirements System Requirements Architecture Hardware Layer Software Layer Applications with Graphical User Interface The Databases Subsystems Timing System Architecture Diagnostics Beam Line Controls The Control System for the Pre-injector (Microtron) Power Supplies (PS)	12-3 12-3 12-3 12-4 12-4 12-6 12-6 12-6 12-9 12-11 12-11 12-11 12-11 12-12 12-16 12-17

		SESAME	
	12.6.2	Radio Frequency System	12-19
	12.6.3	Vacuum Controls	12-19
	12.6.4	Diagnostics	12-19
	12.6.5	The Timing System	12-20
	12.6.6	Other Controls	12-20
	12.7	Estimated I/O	12-20
	12.8	Control Room	12-21
	12.9	Network	12-21
		References	12-21
13.	SITE, BUILDING AND INFRASTRUCTURE		13-1
	13.1	Introduction	13-1
	13.2	Site Investigation and Geotechnical Evaluation	13-4
	13.3	Design of Building Foundation	13-4
	13.4	The SESAME Building	13-5
	13.5	Infrastructure	13-13
	13.4	Cooling System	13-19
	13.4.1	Capacity for the Cooling System	13-21
14.	RADIATION SHIELDING		14-1
	14.1	Introduction	14-1
	14.2	Safety and Dosage Limit	14-1
	14.3	Shielding Design	14-1
	14.3.1	Ionising Radiation	14-1
	14.3.2	Shielding Calculations	14-2
	14.3.2.1	Lateral Shielding	14-3
	14.3.2.2	Perpendicular Shielding	14-4
	14.3.2.3	Shielding for Sky-Shine	14-5
	14.4	Considerations for BeamLines Shielding and Induced Activity	14-6
	14.5	Radiation Monitoring and Personnel Protection System	14-6
	14.6	Conclusions	14-6
		References	14-7